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Hiro: multi- fingered haptic interface robot and

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Review of gifu hand and its application -

Table Of Contents > Review of Gifu Hand and Its a five-fingered haptic interface robot control of multi-fingered robot hand .

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Compliant multi- fingered passively adaptive

Multidiscipline Modeling in Materials and Structures, in multi-fingered robotic hands, applications in robotics, two-fingered grippers could

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Five fingers haptic interface robot hiro: design,

Multifinger haptic interface has a higher potential for the above mentioned applications Hand Haptic Interface Robot, Multi-Fingered Haptic Interface

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Design and control of the four- fingered hand -

Design and Control of the BUAA Four-Fingered Hand Y. Zhang, This research presents a multi-fingered hand and palm and mechanical interface to a robot arm.

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Haptic displays - scholarpedia

the term Haptic Displays refers to interfaces In The Human Hand as an Inspiration for Robot Hand Development of Two-Handed Multi-finger Haptic Interface

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Wearable haptics - wearable sensors - chapter 1.3

and wearable haptics can be utilized as a part of is a two-handed multi-finger haptic interface Two-fingered haptic device for robot hand

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Fokus robotic finger in der digitalen

be used to construct multi-fingered robotic hands with high degrees of freedom puts forward a novel idea of robotic finger, multisensory electronic self

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Virtual robot teaching for humanoid both- hands

Virtual Robot Teaching for Humanoid Both-Hands Robots Using Multi-Fingered Haptic Interface. By Haruhisa Kawasaki, Tetsuya Mouri and Satoshi Ueki

Citeseerx citation query anthropomorphic robot

Abstract This paper presents a lightweight 328 g anthropomorphic robot hand multi-fingered haptic interface robot applications. A multi-fingered haptic

Virtual robot teaching for humanoid both- hands

Virtual Robot Teaching for Humanoid Both-Hands Robots to bimanual tasks using both-hand multi-fingered haptic interfaces. Control Applications

Robot hands and multi-fingered haptic interfaces

Robot Hands and Multi-Fingered Haptic Interfaces is a monograph focusing on the comparison of human hands with robot hands, the fundamentals behind designing and

Follow science | design and development of two

Design and development of two concepts for a 4 DOF portable haptic interface with active and passive multi robot hand. The thumb and haptic interface for the

J kenneth salisbury, jr.'s profile | stanford

Enabling Multi-finger, Multi-hand Virtualized Grasping Barbagli, Robot Hands, Arms and Haptic Interfaces Salisbury, Fundamentals of Dextrous Manipulation

Robot hand - unit for research - products, haptic

HIRO III applications include the THE WORLD S FIRST FIVE-FINGERED HAPTIC INTERFACE ROBOT. Haptic The multi-fingered humanoid Gifu Hand was used

Controlled compliance haptic interface using

Controlled Compliance Haptic Interface Using Electro of applications are needing this type of motion at the corresponding locations at the robot hand.

The human hand as an inspiration for robot hand

"The Human Hand as an Inspiration for Robot Hand Development applications and Finger Using a Multi-Fingered Haptic Interface / Takahiro

Robot hand - unit for research - home

LIGHT AND COMPACT ROBOTIC HANDS FOR A RANGE OF APPLICATIONS. multi-fingered, humanoid robot hands. type robot hand, HIRO III serves as a haptic interface

Patent us4795296 - hand-held robot end effector

A single tactile area of the operator's hand, such as one finger, Hand-held robot end effector controller having movement and Haptic interface device and

Dynamic simulation of multi- fingered robot hands

In dextrous manipulation of multi-fingered robot hands, robot hands have many potential applications in of multi-body simulations for haptic

Mixed control of multi- fingered haptic interface

Abstract This paper presents a mixed control of multi-fingered haptic interface robot The interface is placed opposite the human hand and

Doi:10.4028/www.scientific.net/ssp.144.1 multi-

A multi-fingered haptic interface has robot named HIRO II, which consists of a hand with applications. A multi-fingered haptic interface

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Understanding the human hand for advancing robotic

Overview. Speakers Abstracts. Contributors Abstracts. Understanding the Human Hand. for Advancing Robotic Manipulation Workshop at Robotics: Science and Systems

Asme dc | proceedings | idetc/cie2006 | volume 2:

Design and Development of Two Concepts for a 4 DOF Portable Haptic Interface With Active such as a robot hand. 4 DOF haptic interface for the index finger is

Startup spotlight: prensilia developing robot

Jul 17, 2013 new robotics companies from robot hands could have applications in many of freedom in the hand. In Azzurra, one finger

Two- fingered haptic device for robot hand

Development of multi-fingered universal robot Hand with torque limiter and Applications, Human using a five-fingered haptic interface

Haptic object recognition using a multi- fingered

Abstract While complex hands seem to offer generality, simple hands are more practical for most robotic and telerobotic manipulation tasks, and will remain so for the

Patent us7168748 - intelligent, self-contained

While the invention has focused on an intelligent, self-contained robotic hand, Haptic interface handle with force Multi-fingered type hand device:

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Multisensory interface for 5d stem cell image

The HIRO III Five Fingered Haptic Interface Robot We have developed a new multi-sensory interface for Kojima F. Multipoint haptic device for robot hand

Robotic hand using servo motors: robotics &

Read about robotic hand engineering using our of 16 mm were selected for the four-finger robotic hand. about Robotic Applications involving dc

Researchers develop robot that lets them feel

Jun 02, 2014 Their device consists of a five-fingered haptic hand connected to a robot arm "Softness Display by a Multi-Fingered Haptic Interface Robot," by

Haptics: neuroscience, devices, modeling, and

Neuroscience, Devices, Modeling, and Applications Handed Multi-finger Haptic Interface Fingered Robot Hand Teleoperation Using Desktop Haptic

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J Kenneth Salisbury, Jr. is on CAP Network. Multi-Contact Haptic Interaction with Deformable Objects: Robot Hands, Arms and Haptic Interfaces Salisbury, K.,

Haptic - psychology wiki

Various haptic interfaces for medical simulation may prove The Shadow Dextrous Robot Hand uses the Realistic Multi-Finger Haptics Haptics Research at